



Factory Acceptance Test (FAT) Procedures & Formats - Substation Automation System



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ABOUT THIS DOCUMENT

PURPOSE OF THIS DOCUMENT

This document shall be used as a standard for conducting all tests during the Factory Acceptance Test (FAT) for the typical Substation Automation System (SAS) of every substation as per POWERGRID requirements and specifications.

The aim of the Factory Acceptance Test (FAT) is to demonstrate equipment and functionality as well as the approval of the system-parameterization by POWERGRID to reduce the change requests during commissioning at site. The general philosophy shall be to deliver a system to site only after it has been thoroughly tested and its specified performance has been verified, as far as site conditions can be simulated in a test lab.

During FAT the entire Sub-station Automation System including the complete control and protection system to be supplied shall be tested for complete functionality and configuration in the factory itself for both green field and brown field projects. The extensive testing shall be carried out during FAT. The purpose of Factory Acceptance Testing is to ensure defect free installation at site. No major change in configuration/setting of system is envisaged at site.

In case of extension/Augmentation packages, the existing make SCADA system of the substation where extension is proposed shall be used to carry out the validation of extension bays signals, control commands, etc.

This document details the equipment and functions under test and the corresponding test methods as well as the test documentation.

WHO SHOULD USE THIS DOCUMENT

This document needs to be used by the Vendor representatives (Q&I, Engg, Factory) for Factory acceptance test as per the project requirement. This approved document will be followed by the Vendor Representatives (Q&I, Engg, Testing) and POWERGRID representatives to test and evaluate the complete system.

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1. GENERAL

INTRODUCTION

The purpose of this document is to define the Factory Acceptance Test procedures of Substation Automation System (SAS) for supplied by the Vendor to POWERGRID.

The tests are performed by Vendor and each test, or set of tests as appropriate, is covered by an approval stage, which will be signed off upon completion by Vendor and POWERGRID representatives.

Comments are noted in separate Observation and correction reports (snag list) attached as annexure.

2. PRE-FAT – PREREQUISITES

2.1. ENGINEERING DOCUMENTS

Purpose:

This test verifies that the correct manufacturing drawings and documentation for the equipment/system under the test will be used during the Factory Acceptance Test.

Procedure

1. Vendor shall prepare NTAMC signal list and submit the same for approval during detail engineering.
2. Verify that approved drawings (printed and soft copies) of all assembled equipment are present.
3. Verify that the detailed signal list for Local SAS and NTAMC SCADA as per POWERGRID specimen signal list is available with IEC 61850 & IEC 60870-5-104 addresses and display text as per the list.
4. Verify that the detailed GOOSE matrix with publisher and subscriber details is available.
5. Verify all required hardware and software manuals are present.
6. Guaranteed Technical Particulars (GTPs) as approved by POWERGRID are included in Appendix A for reference.
7. A copy of Customer Technical Specification for reference is made available in the FAT room.
8. Availability of the approved Drawing list in the FAT room.

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Date:	Date:

Drawing Verification Log:

SI No	Description	Drg No.	Checked
1	Standard Approved MQP		<input type="checkbox"/>
2	Approved FAT Procedure		<input type="checkbox"/>
3	GTP-Guaranteed Technical Particulars		<input type="checkbox"/>
4	Complete SAS Architecture Standard General Technical Particulars for SAS		<input type="checkbox"/>
5	Hardware specification		<input type="checkbox"/>
6	Approved HMI Signal List		<input type="checkbox"/>
7	Approved NTAMC Signal List		<input type="checkbox"/>
8	Approved IP address List as received from POWERGRID		<input type="checkbox"/>
9	Functional Design Specification		<input type="checkbox"/>
10	Exported HMI signal list file in spreadsheet/CSV format.		<input type="checkbox"/>
11	Exported NTAMC signal list file in spreadsheet/CSV format.		<input type="checkbox"/>
12	VLAN Architecture drawing (If applicable)		<input type="checkbox"/>
13	Matrix for GOOSE messages for each feeder (with publisher& subscriber details, Mac id, APP Id, VLAN as required)		<input type="checkbox"/>
14	Matrix for SV (with publisher & subscriber details, SV ID, Destination mac and VLAN details) in case of Process Bus substation		<input type="checkbox"/>
15	Ethernet Network Configuration Document (RSTP details, VLAN details, Port details etc.)		<input type="checkbox"/>
16	IP Addressing as per Submitted Architecture (by Vendor) based on sr.no.9		<input type="checkbox"/>
17	Single SCD File of the entire substation		<input type="checkbox"/>
18	GA & Scheme of Network Panel(HMI/Gateway/Time sync/DR)		<input type="checkbox"/>
19	Aux BCU Panel		<input type="checkbox"/>
20	CRP (Line/Trafo/BR/LR/BB/BC/TBC/TieEtc)		<input type="checkbox"/>
21	Product Manuals (Installation, Configuration, maintenance, Troubleshooting, detailed diagnostics etc.)		<input type="checkbox"/>
22	Control Room Lay-out		<input type="checkbox"/>
23	Switchyard Panel Room layout drawing		<input type="checkbox"/>
24	Bill of Quantity-Spares		<input type="checkbox"/>
25	Operation and Technical Guide for BCU, Gateway, Server, OWS Software		<input type="checkbox"/>
26	Operation and Technical Guide IED configuration softwares		<input type="checkbox"/>
27	Operation and Technical Guide NMS Software		<input type="checkbox"/>

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

SI No	Description	Drg No.	Checked
28	Operation and Technical Guide Ethernet Switch		<input type="checkbox"/>
29	Operation and Technical Guide Time synchronizing Equipment		<input type="checkbox"/>
30	Operation and Technical Guide Router Cum Firewall		<input type="checkbox"/>
31	Operation and Technical Guide UPS/Inverter		<input type="checkbox"/>
32	Other applicable drgs (not listed above)	Attach the list as annexure	<input type="checkbox"/>

Note: A single SCD file shall be there for the entire substation. For extension projects too, the SCD file shall be a single file after integrating the newer IEDs.

2.2. SAS FAT EQUIPMENTS

For the FAT configuration the following equipment will be present:

Computer type:	Quantity (complete SW installed)				
(Make e.g., Advantech)	Engg./DR PC	Server PC	Client/HMI PC	Gateway PC	Sys log PC
(Model)					

Network components:	Quantity			
	Station Level		Bay/Dia Level	
	Make/Model	Nos.	Make/Model	Nos.
Ethernet Switch				
GPS Time server				
Router cum Firewall				
Networking Panel				
Auxiliary BCU Panel				
Protection & Relay Panels	NA	NA		

Peripheral	Quantity	
	Make/Model	Nos.
Event Printer		
DR Printer (Color)		
Logbook Printer		
Auto-Changeover switch for redundant UPS supply		
UPS (5 kVA)		

Note: These equipment quantities shall be verified w.r.t. Engg. approved SAS Architecture and BOM.

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Date:	Date:

S.NO.	IEDs	Used For Functions	IED Make	IED Model	Quantity
1.	Main-1 Distance Relay	21M1			
2.	Main-2 Distance Relay	21M2			
3.	Transformer Diff. Relay	87T			
4.	Transformer REF Relay	64			
5.	Reactor Differential Relay	87R			
6.	Reactor REF Relay	64R			
7.	Bay Control Unit	BCU			
8.	BB Diff. Relay	87CU/MCU			
9.	Peripheral Unit	87PU/ BU			
10.	LBB Relay	50BF			
11.	Backup Impedance Relay	21R			
12.	Master Trip relay	86A/B			
13.	Auto-reclose Relay	79			
14.	Stand-alone DR	21DR			
15.	TEED Differential Relay				
16.	Controlled Switching Device				
17.	Transformer B/U O/C				
18.	RTCC				
19	SAS Spare Equipments				
	Other applicable equipments (not listed above)				

Notes:

1) All Units should be present with loaded configurations

For an overview drawing of the equipment installed for the FAT please refer to the sec. 2.1.1.

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Signature:	Signature:
Name:	Name:
Date:	Date:

3. STATION LEVEL EQUIPMENT

Software and hardware components are checked to ensure required functionalities. Versions are recorded for later support purposes.

3.1. HARDWARE COMPONENT

The following hardware equipment are to be present during FAT:

- All Bay Control Units as per approved BOQ.
- All Protection Relays as per approved BOQ.
- HMI/Redundant HMI system consisting of redundant servers.
- Time Synchronizing Equipment consisting of GPS Receiver Unit, Antenna, Time Display Unit.
- Substation Controller/Gateway Subsystem
- Color Printer
- LAN switch equipment
- Auxiliary Panel
- UPS

The above equipment are to be as per approved standard GTP

Purpose

To verify that all hardware equipment required in the contract are available in the FAT room for testing.

Procedure

1. Visually inspect units and individual modules for cleanliness and ensure that they are free from damage.
2. Visually inspect the units for correct wiring practices and ensure that they are free from insulation damage.
3. Ensure the equipment is configured for proper point capacity as per approved drawings.
4. Ensure all modules, terminations and cables have the proper location labels as per approved drawings.
5. Ensure that all earth ground and shield connections are correctly bonded in the panels.
6. Ensure all equipment is free from all foreign material (Dust, Solder, droppings etc.)

Hardware Visual Inspections Log:

S.NO.	Equipment	Hardware Specification (CPU/RAM/HDD)	Serial No.	Checked
1	Server Workstation-1			<input type="checkbox"/>
2	Server Workstation-2			<input type="checkbox"/>

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Signature:	Signature:
Name:	Name:
Date:	Date:

S.NO.	Equipment	Hardware Specification (CPU/RAM/HDD)	Serial No.	Checked
3	Operator Workstation-1 with speakers			<input type="checkbox"/>
4	Operator Workstation-2 with speakers			<input type="checkbox"/>
5	Gateway #1			<input type="checkbox"/>
6	Gateway #2			<input type="checkbox"/>
7	Disturbance Recorder PC			<input type="checkbox"/>
8	Sys Log PC			<input type="checkbox"/>
9	Station Ethernet Switch			<input type="checkbox"/>
10	Router Cum Firewall			<input type="checkbox"/>
11	Color Laser JET Printer			<input type="checkbox"/>
12	Dot Matrix printer			<input type="checkbox"/>
13	GPS Receiver Unit			<input type="checkbox"/>
	Other applicable equipments (not listed above)			

Panel Visual Inspections Log:

S.NO.	Equipment	Serial No.	Circuit Name	Quality of Wiring	Checked
1.	Networking Panel		Networking Panel		<input type="checkbox"/>
2.	Aux. Panel		Aux. Panel		<input type="checkbox"/>
3.	Inverter				<input type="checkbox"/>
4.	Modem				<input type="checkbox"/>
5.	----				<input type="checkbox"/>
6.	----				<input type="checkbox"/>
	Other applicable Panels (not listed above)				<input type="checkbox"/>

3.2. SOFTWARE COMPONENTS

The Software to be used will include the following applications/capabilities:

- The BCU/IED with IEC 61850 (Server/Client) capability.
- HMI & Server with latest Version with IEC 61850 (Client) capability.
- Gateway with latest Version with IEC 60870-5-101 & 104 capability.

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Date:	Date:

Configuration files shall be downloaded prior to commencement of tests and shall be the actual configuration files for individual S/S.

3.2.1. FIRMWARE VERIFICATION

Purpose

To verify and record that the Equipment Firmware used in the FAT.

Procedure

Using Device Display verify all BCU/IED equipment firmware version.

Firmware Verification Log.

S.NO.	Equipment	Model	Operating System/Firmware	Checked
1	OWS-1 & 2			<input type="checkbox"/>
2	SERVER 1 & 2			<input type="checkbox"/>
3	Gateway-1&2			<input type="checkbox"/>
4	DR PC			<input type="checkbox"/>
5	Ethernet Switches			<input type="checkbox"/>
6	Firewall Cum Router			<input type="checkbox"/>
7	GPS Receiver			<input type="checkbox"/>
8	Color Laser JET Printer			<input type="checkbox"/>
9	Dot Matrix Printer			<input type="checkbox"/>
10	Voltage Level_BCU_BAY No.			<input type="checkbox"/>
11	Voltage Level IED's (IEC61850 Compliant) for Dia			<input type="checkbox"/>
	Other applicable equipments (not listed above)			

Note: Record all the TCP/IP Devices & IED devices(Protection, BCU, CSD, RTCC,etc) model & Firmware version which are connected in the substation

3.2.2. IP ADDRESS VERIFICATION

SCADA Devices - IP Addresses

IP address has to be kept as per the list provided shared by POWERGRID. This should be checked at each device user interface.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Station level equipment:

Designation	N/W Name	Mac Id	IP Address				Checked
SERVER 1			172	16	55	1	<input type="checkbox"/>
SERVER 2							<input type="checkbox"/>
OWS1							<input type="checkbox"/>
OWS2							<input type="checkbox"/>
EWS/DR PC							<input type="checkbox"/>
SDC1(If Applicable)							<input type="checkbox"/>
SDC2(If Applicable)							<input type="checkbox"/>
GATEWAY1							<input type="checkbox"/>
GATEWAY2							<input type="checkbox"/>
GPS Time Server 1							<input type="checkbox"/>
GPS Time Server 2							<input type="checkbox"/>
Ethernet Switch 1							<input type="checkbox"/>
Ethernet Switch 2....n							<input type="checkbox"/>
Event Printer							<input type="checkbox"/>
Color Laserjet Printer							<input type="checkbox"/>
Router cum Firewall 1							<input type="checkbox"/>
Router cum Firewall 2							<input type="checkbox"/>
Other applicable equipments (not listed above)							<input type="checkbox"/>

Protection & Control IEDs:

RELAY'S NAME	N/W NAME	GOOSE ID	IP Address				Checked
P444_-----Line			172	16	55	1	<input type="checkbox"/>
							<input type="checkbox"/>
							<input type="checkbox"/>
							<input type="checkbox"/>
							<input type="checkbox"/>

Note: Record all the TCP/IP Devices & IED devices (Protection, BCU, CSD, RTCC,etc) model & Firmware version in the substation

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Signature:	Signature:
Name:	Name:
Date:	Date:

4. TEST EQUIPMENT PREPARATION

The following equipment is required to conduct the test.

- EWS/DR PC installed with all configuration application of IEDs utilized in the project.
- SAS server-1 &2 installed with required SCADA & other softwares as required.
- Gateway -1&2 installed with required SCADA & other softwares as required.
- NMS software installed in the DR PC
- Ethernet switch configured with Proper VLAN, Bridged priority, Edge port and managed as required and documented properly wherever applicable.
- Hand-held Digital Multi-meter suitable for AC/DC with peak-hold and continuity tester
- Digital Clamp-on Meter suitable range for secondary current measurement
- Three phase injection KIT (Relay Test Kit) for supplying 3 phase current and voltage.
- 4-20 mA Injection Kit
- Protocol Analyzer & simulator as applicable (IEC 101/104, Wireshark & etc)

4.1. TEST EQUIPMENT INSPECTION

Purpose

To ensure that the Test Equipment to be used is operational and has valid calibration.

Procedure

Visual inspection of calibration stickers and certificates. Power up and verification that units are operational.

Test Equipment Inspection Log:

S.NO.	Equipment	Calibration Check	Device Power On	Checked
1	3 Phase Injection Kit			<input type="checkbox"/>
2	Precision Hand-held Digital Multi Meters			<input type="checkbox"/>
3	Digital Clamp-on meter			<input type="checkbox"/>
3	Insulation Resistance Tester			<input type="checkbox"/>
4	220V DC Source for powering up all SAS Panels			<input type="checkbox"/>
5	4-20 mA Injection Kit			<input type="checkbox"/>

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Date:	Date:

4.2. POWER CHECKS

Purpose

To ensure that the SAS equipments installed in the panels & control rooms are operating when connected to the nominal specified power supply (220 V AC/DC).

Setup/Program

Perform the steps below to confirm correct operation of all equipment connected to the powersupplies.

Procedure

1. Verify that all 220V AC/DC equipments are powered at the nominal AC/DC supply voltage input. Using a Digital Multimeter verify that the nominal AC/DC supply voltage is present.
2. Verify that there are no abnormalities seen when the equipment are turned ON.

Power Checks Log:

S.NO.	Panel	Equipment	Device Power ON	Checked
1	NA	Server-1		<input type="checkbox"/>
2	NA	Server-2		<input type="checkbox"/>
3	NA	HMI-1		<input type="checkbox"/>
4	NA	HMI-2		<input type="checkbox"/>
5	NA	DR PC		<input type="checkbox"/>
6	NA	Gateway-1		<input type="checkbox"/>
7	NA	Gateway-2		<input type="checkbox"/>
8	NA	Laser JET Printer		<input type="checkbox"/>
9	NA	Dot Matrix Printer		<input type="checkbox"/>
10	Networking Panel	Auxiliaries (Lighting etc), LAN Switches, Gateway		<input type="checkbox"/>
11	Relay Panel	Relays and Wiring diagram		<input type="checkbox"/>

5. FUNCTIONAL TESTING

General Substation Automation System (SAS) is a combination of different bay control units and protection devices with a central operator placed as Human-Machine-Interface (HMI) and central data storage and acquisition. These components and its connections are shown in the System Architecture. For SAS-FAT configuration is selected to check

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the basic system functions and the co-operation between the different components. The test procedure will show the proper function of the system in general. All decentralized I/O devices (bay control units and protection devices) are provided for this test. A complete test of all I/O signals (see SAS signal list) is the objective of this test. All modules are tested by type tests in general and by test routines during manufacturing.

5.1. START-UP BEHAVIOR AND SAS SYSTEM AVAILABILITY

For the following equipment the start – up times are measured to check the performance. The timing of the station controllers starts with switching on the power supply and finishes after reaching the working condition “RUN”. The timing of the Operator Workstation starts with switching on the power supply. The computer will then start - up automatically without registering to Windows or manual start of any software. The timing finishes after reaching the start picture of the application software where the user has to register with the password. The timing of the Engineering PC and Protection Interface PC starts with switching on the power supply and finishes after successful achievement of the working condition.

Note: This test has to be done when all bays along with all signals have been configured and the same are reporting in HMI.

System Start-up	Checked	Start up Time	Comments see log sheet no.
Server-1 (Switch on the relevant MCB Server-1 Workstation boots up and SCADA starts automatically)	<input type="checkbox"/>		
Server-2 (Switch on the relevant MCB Server-2 Workstation boots up and SCADA starts automatically)	<input type="checkbox"/>		
Operator Workstation 1 (Switch on the relevant MCB OWS-1 Workstation boots up and SCADA starts automatically)	<input type="checkbox"/>		
Operator Workstation 2 (Switch on the relevant MCB OWS-2 Workstation boots up and SCADA starts automatically)	<input type="checkbox"/>		
Engineering/DR PC (Switch on the relevant MCB Engineering Workstation boots up and NMS starts automatically)	<input type="checkbox"/>		
Gateway 1 (Switch on the relevant MCB Gateway-1 Workstation boots up and SCADA starts automatically and Data Transmission to RCC/RLDC should resume automatically)	<input type="checkbox"/>		Data Transmission to NTAMC/RCC/RLDC should resume automatically
Gateway 2 (Switch on the relevant MCB)	<input type="checkbox"/>		Data Transmission to NTAMC/RCC/RLDC should resume automatically

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Date:	Date:

Gateway-2 Workstation boots up and SCADA starts automatically and Data Transmission to RCC/RLDC should resume automatically)			
Complete system start up	<input type="checkbox"/>		Black Start

Time Synchronization Verification

After start-up of all devices the error free operation, communication and time synchronization of components is checked on the SCADA displays.

S.NO.	System Start-up	Checked
1.	Time synchronization of Substation controllers / PCs	<input type="checkbox"/>
2.	Time synchronization of connected IEDs	<input type="checkbox"/>
3.	Communication to Bay Control Unit	<input type="checkbox"/>
4.	Communication to Protection Devices	<input type="checkbox"/>
5.	Event list printer	<input type="checkbox"/>
6.	Hardcopy color/ Logbook printer	<input type="checkbox"/>
7.	Communication with remote control centres	<input type="checkbox"/>

5.2. MONITORING AND CONTROL

5.2.1. BCU – DISPLAYS AND HANDLING.

General layout, handling and control of typical feeder BCUs is demonstrated and checked under this chapter. The displayed SLD is cross checked against the approved SLD/ Mimic SLD.

BCUs for _kV Level	Checked	Comments see log sheet no.
Basic/control display for OHL FEEDER	<input type="checkbox"/>	
Basic/control display for TRANSFORMER FEEDER	<input type="checkbox"/>	
Basic/control display for LINE REACTOR FEEDER	<input type="checkbox"/>	
Basic/control display for BUS REACTOR FEEDER	<input type="checkbox"/>	
Basic/control display for TIE BAY/TBC	<input type="checkbox"/>	
Basic/control display for AUXILIARY System	<input type="checkbox"/>	
Basic/control display for BUS COUPLER	<input type="checkbox"/>	
Basic/control display for BUS SECTION	<input type="checkbox"/>	
Event list	<input type="checkbox"/>	
Alarm list	<input type="checkbox"/>	
Analogue measurement list	<input type="checkbox"/>	

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BCUs for__kV Level	Checked	Comments see log sheet no.
Metering list	<input type="checkbox"/>	
Alarm limits	<input type="checkbox"/>	
Handling of displays, control and menu	<input type="checkbox"/>	
Changing V,I,f – limits: - current >limit 1 - current >limit 2 - voltage >limit 1 - voltage <limit 1 - frequency >limit 1 frequency <limit 1	<input type="checkbox"/>	
BCUs for__kV Level	<input type="checkbox"/>	

5.2.2. HMI – USER ADMINISTRATION & ACCESS RIGHTS

Access rights form the basis for safety and security of the overall system with restricted access boundaries for monitoring, control as well as access to specified applications. Access rights are allotted via usernames with password authentication.

Complete flexibility allows for authorization across various screens for viewing access, specific application access, down to individual switching device operation access.

A multi-level login Active directory is implemented in SCADA. There are 4 different levels of access. Without login, there is no possibility to open any display. The different access levels are implemented as shown in following table:

Purpose

To verify that the OWS & HMI system has Security Classes, that are enabled and configured properly.

Setup

- Ensure that the HMI Servers are running.
- Ensure that OWS PCs are running.
- Ensure that PCs are connected to the Network.

Procedure

1. Start Client, by default the user will be logged in as Blank.
2. Verify that this user class has proper access level as per HMI Security Classification.

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Name:	Name:
Date:	Date:

3. Go to any bay detail screen. Verify if access to tool bar and object controls are according to that allowed in the access level logged in.
4. Repeat steps 1 to 3 for the other HMI Usernames (Operator, Engineer, Administrator)
5. Repeat steps 1 to 4 for the other Workstations (OWS-1 &2, Server-1&2, Gateway-1&2)
6. Function is tested by clicking on the corresponding buttons or switching devices and checking of SCADA “No permission” – notifications.

HMI Access Level:

Access Level	Monitor	Operator	Engineer	Admin	Checked	Comment s see log sheet no.
Display System Status & View Screens	Yes	Yes	Yes	Yes	<input type="checkbox"/>	
Controls – CB, Isolators	No	Yes	Yes	Yes	<input type="checkbox"/>	
Acknowledge/Clear Alarms	No	Yes	Yes	Yes	<input type="checkbox"/>	
Change HMI Config.	No	No	No	Yes	<input type="checkbox"/>	
Create/Disable/Delete User Account	No	No	No	Yes	<input type="checkbox"/>	
Change User Profile/Access Level	No	No	No	Yes	<input type="checkbox"/>	
Maintenance mode	No	No	Yes	Yes	<input type="checkbox"/>	
Reset lockout relay	No	Yes	Yes	Yes	<input type="checkbox"/>	
Interlocking bypass	No	No	Yes	Yes	<input type="checkbox"/>	
Sync. Check Bypass	No	No	Yes	Yes	<input type="checkbox"/>	
Auto-reclosure	No	No	Yes	Yes	<input type="checkbox"/>	
Auto sequence	No	No	No	Yes	<input type="checkbox"/>	
Shut down the system	No	No	Yes	Yes	<input type="checkbox"/>	

Automatic Logout

Verify Automatic Logout after 30 min idle time is provided for all access rights.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.2.3. HMI – DISPLAYS AND HANDLING

Check that the displays are in accordance with POWERGRID requirements. General layout and handling are demonstrated and checked. Overview and control pictures are cross-checked against the approved substation SLD.

Purpose

To verify that the Single Line Diagram and Bay Detail Screens on the OWS/HMI system are configured properly and are in correct operating condition.

Setup

1. Ensure that the HMI Servers are running.
2. Log in as an “Operator”.

Procedure

1. Verify the layout of each SLD on the OWS/HMI.
2. Verify the device number, device description and device symbol for each device.
3. Verify all displayed analog and digital values on the detailed bay view screens.
4. Click on each device object and confirm that the respective popup screen or bay/view detail screen is displayed.
5. Repeat steps 1 to 4 for each SLD / Detailed Bay View.

HMI Screen Verification	Checked	Comments see log sheet no.
Handling of screen/picture selection	<input type="checkbox"/>	
Display for Station overall SLD	<input type="checkbox"/>	
Display for__ kV overview:	<input type="checkbox"/>	
- ____ kV substation overview	<input type="checkbox"/>	
- ____ kV single line diagram view	<input type="checkbox"/>	
Display for__ kV overview:	<input type="checkbox"/>	
- ____ kV substation overview	<input type="checkbox"/>	
- ____ kV single line diagram view	<input type="checkbox"/>	
Display of Operations counter for PLCC, CB, LA	<input type="checkbox"/>	
Auxiliary LVAC view & control	<input type="checkbox"/>	
Firefighting system Signals View & control	<input type="checkbox"/>	
Auxiliary DC system view	<input type="checkbox"/>	
Display of Measurement Trends (Real-time and Historical)	<input type="checkbox"/>	
Display of maintenance mode	<input type="checkbox"/>	
Display of safety tagging	<input type="checkbox"/>	
Display of Network/LAN overview	<input type="checkbox"/>	
Display of typical bay communication (Ring)	<input type="checkbox"/>	
Display of event list	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

HMI Screen Verification	Checked	Comments see log sheet no.
Display of alarm list	<input type="checkbox"/>	
Handling of screen/picture selection	<input type="checkbox"/>	
Basic/ Control display for Kiosk Air Conditioning System	<input type="checkbox"/>	
Basic Control display for Online monitoring System for Transformers & Reactors	<input type="checkbox"/>	
Basic /Control display for Control witching Device	<input type="checkbox"/>	
Busbar Colouring as per Live condition	<input type="checkbox"/>	
CVT/CT Monitoring	<input type="checkbox"/>	
Transformer Bank with Tap changer Operation	<input type="checkbox"/>	
Bay Authority level to be checked from Local/Remote/Station/RCC	<input type="checkbox"/>	
Busbar Colouring for the dynamic voltage changes	<input type="checkbox"/>	

Note- In case of extension/Augmentation packages, the existing make SCADA system of the substation where extension is proposed shall be used to carry out the validation of extension bays signals, control commands, etc., with the extension bays configured as the only bays that exist in the substation. For this purpose, the existing SCADA system can be installed on a laptop. Further after completion of FAT, the verified SCADA configuration shall be used for addition into the existing SCADA at site.

5.2.4. INSPECTIONS OF HMI TYPICAL BAY SCREENS

Validation of electrical views

Purpose

To verify that the Single Line Diagram and Bay Detail Screens on the OWS/HMI system are configured properly and are in correct operating condition.

Setup

1. Ensure that the HMI Servers are running.
2. Log in HMI/OWS as an “Operator” .

Procedure

1. Verify the layout of each SLD on the OWS/HMI.
2. Verify the device number and device description for each device.
3. Verify all displayed analog and digital values on the detailed bay view screens.
4. Click on each device object and confirm that the respective popup screen or bay/view detail screen is displayed.
5. Repeat steps 1 to 4 for each SLD / Detailed Bay View.

Bay screens _____kV	Checked	Comments see log sheet no.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

(Naming, SCADA numbers, status indications, measurement items to be checked)		
___kV LINE FEEDER	<input type="checkbox"/>	
___kV TRANSFORMER FEEDER	<input type="checkbox"/>	
___kV BUS REACTOR	<input type="checkbox"/>	
___kV LINE REACTOR	<input type="checkbox"/>	
-----	<input type="checkbox"/>	
-----	<input type="checkbox"/>	
Bay screens ___kV (Naming, SCADA numbers, status indications, measurement items to be checked)	Checked	Comments see log sheet no.
___kV LINE FEEDER	<input type="checkbox"/>	
___kV TRANSFORMER FEEDER	<input type="checkbox"/>	
___kV SHUNT REACTOR	<input type="checkbox"/>	
___kV BUS REACTOR	<input type="checkbox"/>	

Note:

1. **Verify Controlling of each equipment and status of changes.**
2. **Verify that SW interlock – Normal/Bypass**
3. **Safety Tagging for each bay checking**
4. **AR ON/OFF command checking**
5. **CSD IN/OUT checking**
6. **86 Reset/Operated checking**
7. **CB 3 Pole & single pole checking**

5.2.5. GIS GAS MONITORING VIEW

Purpose

In this section we will verify that the GIS Gas Monitoring view screen is represented as per requirement and in line with relevant SLDs.

GIS Gas monitoring View verification

Description	Checked
Verify that the “GIS Gas Monitoring view” screen is displayed on the HMI and GSLD in dynamic color in nature.	<input type="checkbox"/>
Verify that the “GIS Gas Monitoring view” is in line with the Gas Compartment scheme.	<input type="checkbox"/>
Simulate SF6 Stage-1 Alarm from BCU & verify it is report as events	<input type="checkbox"/>

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Description	Checked
Verify that this is detected and is displayed in the view.	<input type="checkbox"/>
Simulate SF6 Stage-2, 3 & 4 Alarm from BCU & verify that this is detected and is displayed in the view and as well as reported as events.	<input type="checkbox"/>
Verify that Gas Pressure is indicated for each compartment (if Applicable)	<input type="checkbox"/>

5.2.6. VALIDATION & VERIFICATION OF SIGNALS ON SCADA HMI/GATEWAY

Purpose

To verify that the signals as per the approved signal list provided by POWERGRID have been correctly configured and are appearing on SCADA HMI/GATEWAY as desired.

Prerequisites for the Validation

1. Approved SCADA Signal list for HMI/Server for Substation level
2. Approved RCC-SCADA Signal list for NTAMC for Gateway
3. Goose signal list (Signals between IED, Mac id, APP id, VLAN) by vendor

HMI/NTAMC SCADA Signal Verification

The Detailed signal list based on which the SCADA configuration has been prepared shall be taken and each signal shall first be validated by simulating “HIGH” and “LOW” states one by one (e.g Naming of each signal, appearance of “Valid”, Reset/Set/operated/Healthy, etc status as per the appearance of on-screen validity shall be checked). Any signal appearing as “unknown” / “invalid” shall be flagged and configuration shall be modified for proper validation.

Typical bays to be created in SCADA configuration for each feeders and any changes in any bays should be reflected in all bays. Signal list for each typical bay must be configured with sufficient spare with each IEDs standard so that changes in any of the Typical should reflect in all the other bays.

After validation of signals under SCADA configuration, various protection functions and appearance of the desired signals on SCADA HMI shall be verified.

For certain signals (having Integer type attribute), the on-screen display of text depends on the value fetched from IED, (e.g. **Auto-reclose status from function RREC wherein the value of AutoRecSt 1 denotes ready, 2 denotes Auto-reclosure in-progress, etc**).

All types of text displays with different inputs shall be verified by simulation of the state and their naming should be configured in user understandable manner. (e.g. **Auto-reclose status from function RREC wherein the value of AutoRecSt 1 denotes ready so text should be “Auto Reclose Ready”, etc**)

Note:

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

1. For verifying the HMI/SCADA signals for each bays, the simulation may be done from the respective devices. If the devices are not available due to unavoidable situation, same may be done using the Simulators like Omicron Scout, IEC browser etc.
2. For extension/Augmentation projects, The existing project typical has to be taken as reference and configuration has to be done accordingly to reflect the existing projects signal name & appearance.

GATEWAY DATABASE CONSISTENCY CHECKS

There are three IEC-104 ports on each Gateway for communication with NTAMC, Backup NTAMC & RTAMC Control Centers. Reporting of all signals is required to checked on all six ports through database consistency checks as per the procedure below.

IEC Master Simulation Software is to be connected on each port one by one and data is to be polled through General Interrogation. Output from all six ports consisting of all data points with IEC-104 address and ASDU to be dumped in an excel file and to be checked for count of signals with identical reporting. Mismatch if any between all six ports to be rectified.

After successful completion of this test, no modification of database is allowed.

Description	Checked	Comments see log sheet no.
Gateway Database Consistency Final Database Version _____	<input type="checkbox"/>	

Host firewall of remote gateways shall be enabled and configured as per baseline configuration.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Control Authority Transfer Signal Verification:

For Main System:

	STATUS- MAIN CONTROL ON NTAMC	STATUS - MAIN CONTROL ON RTAMC	STATUS - MAIN CONTROL ON BNTAMC	CHECKED	Comments see log sheet no.
COMMAND FROM SCADA FOR MAIN SYSTEM CONTROL AT NTAMC	SET	RESET	RESET	<input type="checkbox"/>	
COMMAND FROM SCADA FOR MAIN SYSTEM CONTROL AT RTAMC	RESET	SET	RESET	<input type="checkbox"/>	
COMMAND FROM SCADA FOR MAIN SYSTEM CONTROL AT BNTAMC	RESET	RESET	SET	<input type="checkbox"/>	
DEFAULT STATUS	SET	RESET	RESET	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

For Auxiliary System:

	STATUS- AUX CONTROL ON NTAMC	STATUS -AUX CONTROL ON RTAMC	STATUS -AUX CONTROL ON BNTAMC	CHECKED	Comments see log sheet no.
COMMAND FROM SCADA FOR AUX SYSTEM CONTROL AT NTAMC	SET	RESET	RESET	<input type="checkbox"/>	
COMMAND FROM SCADA FOR AUX SYSTEM CONTROL AT RTAMC	RESET	SET	RESET	<input type="checkbox"/>	
COMMAND FROM SCADA FOR AUX SYSTEM CONTROL AT BNTAMC	RESET	RESET	SET	<input type="checkbox"/>	
DEFAULT STATUS	SET	RESET	RESET	<input type="checkbox"/>	

Buffer Synchronization between Main and Standby Gateway:

Substation Gateways are to be configured in Hot-Hot mode i.e. all six remote communication ports are always ready for transmitting data to the master stations (Main NTAMC, Backup NTAMC, RTAMC). At an instance, each control center polls only one of the gateway independently. During gateway switchover from control center, it is to be checked that the signals which have been reported in real time from previous gateway should not report again as buffer event from second gateway. Buffer signals must be synchronized between both gateways.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

	Buffer signals reporting	CHECKED	Comments see log sheet no.
Check Signals reported in real time at SCADA from main gateway and switching over to Standby Gateway (Check for each Master one by one)	Previous event already reported by Main Gateway should not report from Standby Gateway buffer	<input type="checkbox"/>	
Check Signals reported in real time at SCADA from Standby gateway and switching over to Main Gateway (Check for each Master one by one)	Previous events already reported by Standby Gateway should not report from Main Gateway buffer	<input type="checkbox"/>	
Check Signals reporting from buffer after restoration of the link with master station (Check for each master one by one from both gateways)	Previous event should report as buffer as per buffer event capacity	<input type="checkbox"/>	

GOOSE Signal Verification

For all the IEDs subscribing to GOOSE messages from other IEDs (e.g. BCUs, Protection), which are used to perform logical actions, the appearance of **GOOSE fail / GOOSE trouble alarm** shall be configured and verified by making one of the GOOSE message absent, to which the IED subscribes. **(Note: Wherever GOOSE messages configured should be ensured with quality tag configured and failure of the GOOSE signal should reflect in respective subscribed IED as invalid, and alarm appears in SCADA).**

The Voltage selection logics for ICTs & Rector feeders, utilizing GOOSE messages shall also be verified by simulating various switchgear status, which change the selected voltage.

Note:

1. Each GCB of the IEDs has to be verified for every device for the VLAN, App id, Mac id as per the Goose Signal list documentation. Unused GCB/RCB may be may be removed.
2. Wherever available, GOOSE supervision shall be done using LGOS Logical node.
3. GOOSE dashboard may be prepared in HMI for easy monitoring of GOOSE reception for process bus/digital substation.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.2.7. VALIDATION OF HISTORICAL TREND

Purpose

To verify that the Trend in the OWS/HMI system are configured properly and are in correct operating condition.

Setup

Ensure that the HMI servers are running. Go to Trend Screen.

Validation of Historical Trend on OWS/HMI

S.No.	Activity	Checked
1	Verify all Analog signals on trend screen for each feeder configured.	<input type="checkbox"/>
2	Verify that the trend curve on HMI screen for different analog signal has different colors.	<input type="checkbox"/>
3	Verify that the Time Scale for trend curves are user settable.	<input type="checkbox"/>
4	Verify that EHV Lines/ ICT/Reactors/Bus/ LVAC have Predefined trend of current, active and reactive power. Bus have Predefined trend of voltage and frequency.	<input type="checkbox"/>
5	Data archive retrieval is to be checked for proper display of old records	<input type="checkbox"/>

5.2.8. VALIDATION OF REPORTS FUNCTION

Purpose

To verify that the Reports Functions (Historical Report) in the OWS/HMI system are configured properly and are in correct operating condition.

Setup

1. Ensure that the Client & Server is running.

Historical Event Report

1. Generate some Digital / Analog events in BCU.
2. Click on the Reports button present on the HMI/OWS Screen.
3. Select the Range of date by selecting the Start Date and End Date.
4. Verify whether the same generated events have been produced in the Historical Report.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Daily Report (Hourly Instantaneous Value of Analog Data Points)

1. Inject Voltage & Current through 3 Phase Injection Kit to any BCU.
2. Verify the values on the detailed view of the selected BCU.
3. Select the daily Report Button of line BCU.
4. Verify the daily Report have produced Hourly instantaneous Value of the selected BCU. The Maximum and minimum instantaneous value of each selected parameter (with time) shall also be included in the report. This time-tagged max and min data shall be generated from the Trend data of the BCU.
5. Data archive retrieval is to be checked for proper display of old records.

Operation Reports:

Apart from Historical and trend reports of analog values, reports in specified formats as per the requirement of POWERGRID system operation is also to be generated in the standard format provided by POWERGRID. The reports will be periodic logging (15min/01 hourly/ 04 hourly/ 08 hourly etc) of analog/ digital values.

The following reports must be covered as a part of the Reports in prescribed format as per POWERGRID.

1. EHV Feeders (Line, Transformer, Reactor, etc)
2. Transformer Feeder & Reactor Temperatures
3. Online Monitoring equipment values
4. LV System – AC switch board values
5. Kiosk Temperatures
6. Battery charger
7. PLCC/DTPC Counter readings
8. Circuit breaker counter recordings
9. LA counter recordings

5.3. SCADA COMMUNICATION

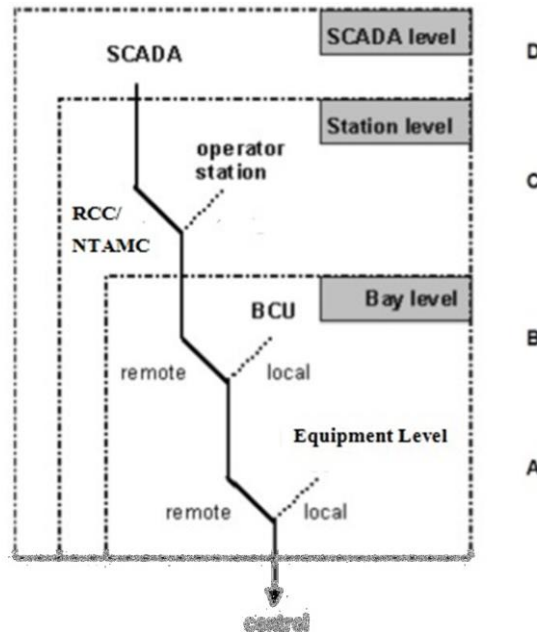
In this chapter the communication to SCADA via IEC101/IEC104/IEC 61850 will be checked. A detailed information test (control authority, commands, and indications) will be done in the chapter following this. SCADA-interface is simulated with test program IEC-Test running on two laptops. With the test program the protocols IEC-101/IEC-104 as well as IEC-61850 can be simulated. Detailed redundancy tests will be performed under **chapter 5.17**.

	Checked	Comments see log sheet no.
Communication checks for -spontaneous information -general interrogation	<input type="checkbox"/>	
- time stamping of indications	<input type="checkbox"/>	
POWERGRID Representative	Manufacturer Representative	
Signature:	Signature:	
Name:	Name:	
Date:	Date:	

- Check response/ refresh time of reporting any data from IED	<input type="checkbox"/>	
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5.4. CONTROL TESTS

Control is possible from Control Panel/LCC Board, BCU, Operator Workstation (1 or 2) and NTAMC/Backup NTAMC/RTAMC. During the test all check back indications from switchgear devices will be simulated by an I/O simulation box. Preconditions for controls are correct switching conditions (synch-check and interlocking). Switching the relevant local/remote switch will be displayed in the event list.



	Checked	Comments see log sheet no.
A. Control from mimic board The mimic board is implemented in the cubicle	<input type="checkbox"/>	
B. Control from BCU Changing the status of local/remote switch on BCU raises an event-on-event list. Control from BCU is only possible if local/remote switch on. BCU is in local position and local/remote switch on mimic board is in remote position. In this position no control from Operator Workstation and SCADA is possible.	<input type="checkbox"/>	
C. Control from Operator Workstation Changing status of local (SCADA) / remote (SCC/RCC) button on Software screen raises an event-on-event list. Control from Operator Workstation is only possible if control is switched to local position and local/remote switch on BCU in Remote and mimic board is in	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

	Checked	Comments see log sheet no.
remote position. In this position no control from SCC/RCC is possible.		
D. Control from SCC/RCC Control from SCC/RCC is only possible if all local/remote switches per bay (on bay- and station level) are in remote position and Local SCADA in Remote position. SCC/RCC interface is simulated with test program IEC Test.	<input type="checkbox"/>	

5.5. CONTROL METHOD

Control of switchgear shall be done from the detailed bay display diagrams in OWS/HMI. The method of man machine dialogue shall be a multi-stage procedure with verification to ensure security of control.

	Checked	Comments see log sheet no.
- Selection of switching device	<input type="checkbox"/>	
- Appearance of selected device control window	<input type="checkbox"/>	
- Selection of switching direction (open/close)	<input type="checkbox"/>	
-Change of the selected device symbol (flashing in selected control direction)	<input type="checkbox"/>	
- Execution of the control	<input type="checkbox"/>	
- Possibility of cancellation at any time	<input type="checkbox"/>	
- Time out of control mode if operator fails to respond	<input type="checkbox"/>	
- Bypassing the command for interlocking/Synchorcheck wherever required		
- Source of control appearance in event list	<input type="checkbox"/>	
- Double object control blocking function for control from HMI/ SCADA level	<input type="checkbox"/>	

5.6. CONTROL OF DUMMY CIRCUIT BREAKER

	Checked	Comments see log sheet no.
- Check of dummy circuit breaker function	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.7. CONTROL OF CIRCUIT BREAKER

“CLOSE” and “OPEN” operation of typical circuit breaker is tested by giving a command from BCU or HMI and checking of the command execution. At the same time, the respective check back indication of switching position is checked at the BCU and HMI. The correct registration in the event list will also be tested. All the bays for each voltage level will be checked. Furthermore, some faults will be simulated (e. g. control authority, CMD interlocked, CMD monitoring time). RCC SCADA interface is simulated with test program IEC-Test.

kV Level	Command	Checked typical				Comments see log sheet no.
		701-52	401-52	***-52	***-52	
765kV	Circuit breaker	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display BCU	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display HMI	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display RCC	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	HMI/NTAMC event list	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
400kV	Circuit breaker	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display BCU	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display HMI	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display RCC	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	HMI/NTAMC event list	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
-----kV	Circuit breaker	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display BCU	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display HMI	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	Control/Display RCC	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
	HMI/NTAMC event list	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

5.8. SYNCH-CHECK

Synchro check-function is parameterized in the BCU. Therefore, control is demonstrated from bay control unit for functionality-check. Positions of bus bar voltage transformer disconnecting switch are simulated by an I/O simulation box and bus bar voltage by a test set (e.g., Relay Test Kit).

Purpose

To verify that Incoming and Running (Reference) voltages are within the synchronizing range before the circuit breaker can close. The circuit breaker will not close if any of the limiting parameters is not within the check synchronizing range. For practical reasons this FAT will not include the testing of Running Voltage selection for the Synchronization.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Setup

1. Set up the BCU to check synchronizing ranges as follows:
 - Phase Differences Specification requirement states Phase Difference shall not exceed 30° (1° Hysteresis).
 - Voltage Difference Specification requirement states Voltage Difference shall not exceed 10% (2% Hysteresis).
 - Frequency difference 0.1 Hz (Connected System).
2. Set up the 3 Phase Injection Kit to supply the Running Voltage & Selected Voltage to BCU TMU card (CT/VT card).
3. Set up the 3 Phase Injection Kit to the following test cases:

Check Synchronization Test Settings

Voltage Difference

Test Case	Voltage Difference in pu	Phase Y Difference in Degrees	Expected Sync Close Results	Checked
1	0.20	40.0	No	<input type="checkbox"/>
2	0.12	40.0	No	<input type="checkbox"/>
3	0.10	20.0	No	<input type="checkbox"/>
4	0.09	20.0	No	<input type="checkbox"/>
5	0.09	17.0	No	<input type="checkbox"/>
6	0.10	16.0	No	<input type="checkbox"/>
7	0.10	15.0	Yes	<input type="checkbox"/>
8	0.05	10.0	Yes	<input type="checkbox"/>

Procedure

1. Select a BCU and corresponding Circuit Breaker to Test.
2. Using the 3 Phase Injection kit, inject the Running & Selected Voltage to the BCU and apply the differences as shown in the above table.
3. Open the Detailed view of the selected Bay on the HMI and verify the voltage references.
4. Initiate the CB Close Request.
5. Verify that the Circuit Breaker closes only when the configured settings are satisfied.

CB	CB Condition	Checked
765KV Circuit Breakers		
701		<input type="checkbox"/>
702		<input type="checkbox"/>
---		<input type="checkbox"/>

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

400KV Circuit Breakers		
401		<input type="checkbox"/>
402		<input type="checkbox"/>
---		<input type="checkbox"/>

The above check sync verification is to be carried out for all possible voltage selection logics for synchronization (e.g, for main bay breaker connected to Bus 1 in one and half scheme, Bus 1 Voltage- Bus 2 Voltage, Bus 1 Voltage - Feeder 1 Voltage, Bus 1 Voltage – Feeder 2 voltage, as may be required in the scheme). These possible voltage selection conditions are required to be simulated either by simulated switchgear or by simulating GOOSE messages published by other BCUs, which are required in the selection logic.

Synchro-check & Synchronism Check

Purpose

To verify that when the following conditions are met, the Synchro-check logic permits the Immediate closure of the Circuit Breaker.

- **Dead Line-Dead Bus**
- **Dead Line-Live Bus**
- **Live Line-Dead Bus**
- **Live Line- Live Bus**

Setup

1. Set up the BCU to check synchronizing settings as follows:

- Presence of Line Voltage (Param1) – 70%
- Absence of Line Voltage (Param2)– 20%
- Presence of Bus Voltage (Param3)– 70%
- Absence of Bus Voltage (Param4)– 20%

Procedure

The absolute values of the two voltages (V_{line} V_{busbar}) must be above or below settable thresholds, to permit the circuit breaker closing. The following voltage controls are available:

- ✓ **V_{line} - No Voltage and V_{busbar} - No Voltage** – (Dead Line-Dead Bus)
- ✓ **V_{line} - No Voltage and V_{busbar} - Healthy Voltage** – (Dead Line-Live Bus)
- ✓ **V_{line} - Healthy Voltage and V_{busbar} - No Voltage** – (Live Line-Dead Bus)
- ✓ **V_{line} - Healthy Voltage and V_{busbar} - Healthy Voltage** – (Live Line-Live Bus)

With **Healthy V_{line}** and **Healthy V_{busbar} TRUE** if the measured voltage is above the threshold $V >$ (param 1 and param 3), and **No voltage V_{line}** and **No voltage V_{busbar}**

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

TRUE if the measured voltage is below the threshold $V <$ (param 2 and param 4). These thresholds are given in % of the nominal voltage value, updated at CT/VT board level.

The selection of the voltage control is made during the configuration phase.

Test Case	Description	Expected Sync Close Results	Checked
DL-DB	In case of the absence of both voltages i.e. V_{line}- No Voltage and V_{busbar}- No Voltage	Yes	<input type="checkbox"/>
DL-LB	In case of the absence of one of the two voltages i.e. V_{line}- No Voltage and V_{busbar}- Healthy Voltage	Yes	<input type="checkbox"/>
LL-DB	In case of the absence of one of the two voltages i.e. V_{line}- Healthy Voltage and V_{busbar}- No Voltage	Yes	<input type="checkbox"/>
LL-LB	In Case of the presence of both voltages i.e. V_{line}- Healthy Voltage and V_{busbar}- Healthy Voltage Set beyond ranges	No	<input type="checkbox"/>
LL-LB	In Case of the presence of both voltages V_{line}- Healthy Voltage and V_{busbar}- Healthy Voltage Set within synchronism ranges	Yes	<input type="checkbox"/>

	Checked	Comments see log sheet no.
Displaying and Handling- BCU	<input type="checkbox"/>	
Displaying and Handling- HMI	<input type="checkbox"/>	

	Checked	Comments see log sheet no.
Live line – dead bus	<input type="checkbox"/>	
Dead line – live bus	<input type="checkbox"/>	
Dead line – dead bus	<input type="checkbox"/>	
Live line – live bus with fulfilled sync conditions (V _{diff} , f _{diff} , angle)	<input type="checkbox"/>	

5.9. CONTROL OF ISOLATOR AND EARTHING SWITCH

“CLOSE” and “OPEN” operation of high voltage switching devices are tested by giving a command from BCU or HMI and checking of the command execution. At the same

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Name:	Name:
Date:	Date:

time, the respective check back indication of switching position is checked at the BCU and HMI. The correct registration in the event list will also be tested. All bay for each voltage level shall be checked. Furthermore, some faults will be simulated (e.g. control authority, CMD interlocked, CMD monitoring time). NCC/RCC-interface is simulated with test program IEC-Test & event list also recorded.

SCADA-interface is simulated with test program IEC-Test wherever required.

5.10. INTERLOCKING (BAY AND STATION BASED)

Control of switchgear devices is only possible if all interlocking conditions are fulfilled. Interlocking conditions are shown in circuit manuals of local control cubicles (For drawing nos. see chapter 2.1). Generally, for demonstration of interlocking the control can be done from bay control unit. As the complete feeder interlocking is checked during SAT of BCU together with primary switchgear, only some selected general functions are shown. Positions of relevant breakers/isolators are simulated by a hardwired I/O simulation box. **The interlocking logic and status for each switchgear should be visible to the operator on OWS/HMI beforehand while operating the respective switchgear.** The validation of interlock condition shall be performed based on the interlock logic visible on the screen.

	Checked	Comments see log sheet no.
Maintenance mode	<input type="checkbox"/>	
Switchgear interlocking	<input type="checkbox"/>	
HMI–display of interlocking conditions along with signals for each switchgear device	<input type="checkbox"/>	

5.11. SWITCHING SEQUENCES FOR GIS (IF APPLICABLE)

Switching sequences are initiated and controlled from the Station Controller. The preconditions for switching sequences are parameterized in BCU. The interruption of the switching sequence can occur due to missing one of the preconditions, either synch-check or interlocking. Correct switching and the corresponding feedback indications will be checked. Randomly, some interlocking conditions will be done in such a way that the switching sequence will be interrupted. The effect will be that the system will wait for the command running time to terminate. **In the event, a list of negative feedback will be recorded indicating the reason for not executing the command i.e., cause of not executing command.**

CONNECT OHL FEEDER TO BB1:		
closing of Isolators & CB		
CONNECT OHL FEEDER TO BB2:		
closing of Isolators & CB		
DISCONNECT OHL FEEDER (Bay):		
opening of Isolators & CB		
CHANGE BUSBAR:		

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Date:	Date:

closing/opening of Isolators		
CLOSE BUS COUPLER :		
closing of Isolators & CB		
OPEN BUS COUPLER :		
Opening of Isolators & CB		

5.12. DIGITAL RTCC FUNCTIONS (IF APPLICABLE)

The Digital RTCC Functions view shows information about the transformer feeder (ICT1-ICTn) of the station. Information about the tap position. Using the control button, a tap position control window will appear. It can be chosen between the automatic and manual mode. The tap position of each transformer feeder can be changed with the top/down slider by using the manual mode. The exit button closes the window.

Properties of Digital RTCC	Checked	Comments see log sheet no.
- Selection of transformer feeder	<input type="checkbox"/>	
- Appearance of selected window	<input type="checkbox"/>	
- Selection of control mode (auto/manual)	<input type="checkbox"/>	
- Send TAP rise/ lower command in manual	<input type="checkbox"/>	
-Checking of Master-Follower/ independent mode	<input type="checkbox"/>	
-Checking of Other RTCC Functions(like WTI,OTI Tempt, Cooler bank events, other configured alarms,etc)	<input type="checkbox"/>	

5.13. EVENT PROCESSING

Events are displayed in chronological order in the event list. All events have date and time tag. Selection of event list on Operator Workstation will show the latest page with the newest event on top and the sorting should be ensured.

Events list should have white background & include all the alarms. . The creation of a reduced list is possible by filter function. Transient conditions (i.e.00/11) will not generate an event, unless a time delay is exceeded it Should be ensured particularly in CB, Isolator, Earth switch & other events where change of events takes in prescribed time to avoid flooding of information.

Purpose

To verify that the Events Points are configured properly and in correct operating condition.

Setup

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

1. Ensure that the HMI Servers are running.
2. Display the Event Screen.

Procedure

1. Select a Digital Input Point from one of the BCUs configured as an Event.
2. Change the state of the Selected Input
3. Verify that an Event is displayed on the Event Screen with proper description and Time Stamp.
4. Time format should be configured as 24hours(hh:mm:ss:000).
5. Acknowledge this alarm.
6. Go to the Event Screen and verify that this alarm is displayed in the list.
7. Verify that the same has been printed on the Dot Matrix Printer.
8. Repeat Steps 1 to 6 for the All the digital Input as per the signal list.

Validation of the Events and Alarm Management on OWS/HMI

S.No	Activity	Checked
1	Verify that separate logs are available for alarm and events	<input type="checkbox"/>
2	Verify that suitable filters (sorting by date, time etc) are provided for both alarms and events	<input type="checkbox"/>
3	Verify that an Alarm and Event is displayed in the Alarm and Event Screen with proper description and Time Stamp	<input type="checkbox"/>
4	Verify the alarm acknowledgement facility and verify that their display changes in alarm viewer according to the alarm status. Persisting alarm shall be distinguishable from acknowledged alarms.	<input type="checkbox"/>

	Checked	Comments see log sheet no.
Event Processing		
- BCU	<input type="checkbox"/>	
- HMI	<input type="checkbox"/>	
Time tagging		
- BCU	<input type="checkbox"/>	
- HMI	<input type="checkbox"/>	
Filter function- date/time		
- message group	<input type="checkbox"/>	
- message text	<input type="checkbox"/>	
- alarm group	<input type="checkbox"/>	
Check naming convention of one typical feeder according signal list		
- hierarchical name	<input type="checkbox"/>	
- signal name	<input type="checkbox"/>	

5.14. ALARM PROCESSING

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Alarms are displayed in chronological order in the alarm list. Selection of alarm list on Operator Workstation will show the latest page with the newest alarm on top of the line. Coloring depends on alarms status (**RAISED – RED , CLEARED- GREEN, AND ACKNOWLEDGED- YELLOW**). Acknowledgement of alarms depends on permissions level (see 2.4.2.2 “HMI – USER ADMINISTRATION & ACCESS RIGHTS)

Purpose

To verify that the Alarms are configured properly and in correct operating condition.

Setup

1. Ensure that the HMI Servers are running.
2. Display the Alarm Screen.

Procedure

1. Select a Digital Input Point from one of the BCUs configured as an Alarm.
2. Change the state of the Selected Input
3. Verify that an Alarm is displayed in the Alarm Screen with proper description and Time Stamp.
4. Time format should be configured as 24hours(hh:mm:ss:000).
5. Acknowledge this alarm.
6. Verify that the same has been printed on the log Printer.
7. Repeat Steps 1 to 6 for the several Digital Input

	Check ed	Comments see log sheet no.
Alarm Processing (RED) - BCU - HMI	<input type="checkbox"/> <input type="checkbox"/>	
Time tagging - BCU - HMI	<input type="checkbox"/> <input type="checkbox"/>	
Filter function- date/time - message group - message text - alarm group	<input type="checkbox"/> <input type="checkbox"/>	
Permission of acknowledgement	<input type="checkbox"/>	
Alarm raised: YELLOW FLASHING	<input type="checkbox"/>	
Alarm cleared: GREEN	<input type="checkbox"/>	
Alarm acknowledged: YELLOW	<input type="checkbox"/>	
Alarm list filtering function (Date & Time, Bay No.)	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.15. ANALOGUE MEASUREMENT HANDLING

Correct displaying of analogue values is checked on the screens of BCU and HMI. A change of analogue quantity is reported to the SCADA master system. Correct displaying of power flow convention is defined and checked. Measurements will be tested from BCU (in feed by a relay test set) as well as from BCU :

	Checked	Comments see log sheet no.
Displaying of analogue values		
- BCU	<input type="checkbox"/>	
- HMI	<input type="checkbox"/>	
Power flow convention	<input type="checkbox"/>	
Real time trends	<input type="checkbox"/>	

Measurement of each Bay:

For e.g.

Checked

CT Ratio: 3000A/1A *

VT Ratio: 400KV/110V *

Current Measurement								
Injected second. Current	Expected measured value	Dead band	Indicated Value					
			R		Y		B	
			BCU	HMI	BCU	HMI	BCU	HMI
0.0A								
0.05A								
0.5A								
1.0A								
1.1A								

Voltage Measurement								
Injected second. Current	Expected measured value	Dead band	Indicated Value					
			R		Y		B	
			BCU	HMI	BCU	HMI	BCU	HMI
6.35V								
31.75V								
63.5V								
70V								
110V								

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Date:	Date:

Frequency Measurement:							
Injected Frequency	Dead band	48Hz		50Hz		52Hz	
		BCU	HMI	BCU	HMI	BCU	HMI
Indicated Value							

Comments see log sheet no.

*CT & PT Ratio as per approved drawing

Power Measurement													
Injected Value	Phase Angle	Active Power				Reactive Power				Power Factor			
		Calculated Value	BCU	HMI	Err. (%)	Expected Value	BCU	HMI	Err. (%)	Calculated Value	BCU	HMI	Err. (%)
	I = U =	V with ref. to I											
	0°									1			
	60°									0.5			
	90°									0			
	120°									-0.5			
	-120°									0.5			
	-60°									-0.5			

Transformer Measurement Values					
Injected		Measured			Checked
Simulator		HMI	Error (%)	Remote Control Center	
Oil Temperature	°C				<input type="checkbox"/>
Winding Temperature HV	°C				<input type="checkbox"/>
Winding Temperature IV	°C				<input type="checkbox"/>
Winding Temperature LV	°C				<input type="checkbox"/>
Oil Temperature	°C				<input type="checkbox"/>
Winding Temperature HV	°C				<input type="checkbox"/>
Winding Temperature IV	°C				<input type="checkbox"/>

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Date:	Date:

Winding Temperature LV °C				<input type="checkbox"/>
..... °C				<input type="checkbox"/>

General Station Analogue Values					
Injected	HMI	Measured SUPERVISORY		Checked	Comments see log sheet no.
		Simulator	Display		
Outside Temp(°C)				<input type="checkbox"/>	
Outside Humidity %				<input type="checkbox"/>	
SCADA Room Temp (°C)				<input type="checkbox"/>	
Telecom Room Temp(°C)				<input type="checkbox"/>	
Battery Room Temp(°C)				<input type="checkbox"/>	
SPR... Temp(°C)				<input type="checkbox"/>	
SPR... Temp(°C)				<input type="checkbox"/>	

Aux system Analogues Values						
Injected	HMI	Measured SUPERVISORY			Checked	Comments see log sheet no.
		Simulator	Display	Error (%)		
Current 220V DC 1 O/PA				<input type="checkbox"/>	
Voltage 220V DC 1 O/P V				<input type="checkbox"/>	
Current 220V DC 2 O/PA				<input type="checkbox"/>	
Voltage 220V DC 2 O/P V				<input type="checkbox"/>	
Current 48V DC 1 O/PA				<input type="checkbox"/>	
Voltage 48V DC 1 O/P V				<input type="checkbox"/>	
Current 48V DC 2 O/PA				<input type="checkbox"/>	
Voltage 48V DC 2 O/P V				<input type="checkbox"/>	
MSB Incomer-1 Voltage	... V				<input type="checkbox"/>	
MSB Incomer-2 Voltage	... V				<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Aux system Analogues Values						
Injected		HMI	Measured SUPERVISORY			Comments see log sheet no.
Simulator		Display	Error (%)	Transmitt ed	Checked	
MSB Bus-1 Votlage	... V				<input type="checkbox"/>	
MSB Bus-2 Votlage	... V				<input type="checkbox"/>	
LVAC Incomer-1 Votlage	... V				<input type="checkbox"/>	
LVAC Incomer-2 Votlage	... V				<input type="checkbox"/>	
LVAC Bus-1 Votlage	... V				<input type="checkbox"/>	
LVAC Bus-2 Votlage	... V				<input type="checkbox"/>	
MSB Incomer-1 CurrentA				<input type="checkbox"/>	
MSB Incomer-2 CurrentA				<input type="checkbox"/>	
LVAC Incomer-1 CurrentA				<input type="checkbox"/>	
LVAC Incomer-2 Current	... V				<input type="checkbox"/>	
LVAC Bus-1 Votlage	... V				<input type="checkbox"/>	
LVAC Bus-2 Votlage	... V				<input type="checkbox"/>	
Diesel Generator Voltage V				<input type="checkbox"/>	
Diesel Generator CurrentA				<input type="checkbox"/>	
-----					<input type="checkbox"/>	
Other Aux system measurements if any					<input type="checkbox"/>	

5.16. CHANGING OF ALARM LIMITS

For supervising the analogue values each measured value shall have high and low alarm limits available. It shall be possible to set each limit independently at the BCU stage. When an alarm limit is detected as having been transgressed an alarm shall be generated and the value displayed on the VDU shall be identified as in alarm status by use of color or other means to the approval of engineer.

	Set point	Checked	Comments see log sheet no.
Voltage	- upper limit: 107% of nominal value	<input type="checkbox"/>	
	- lower limit: 95% of nominal value	<input type="checkbox"/>	
	- processing of alarm limits (color)	<input type="checkbox"/>	
	- hysteresis	<input type="checkbox"/>	

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Signature:	Signature:
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Date:	Date:

	- alarm dead band	<input type="checkbox"/>	
Current	- 1 st upper limit: 1000A for 400&765kV level	<input type="checkbox"/>	
	- 2 nd upper limit: 1500A for 400&765kV Level	<input type="checkbox"/>	
	- processing of alarm limits (color)	<input type="checkbox"/>	
	- hysteresis	<input type="checkbox"/>	
Frequency	- upper limit: 105% of nominal value	<input type="checkbox"/>	
	- lower limit: 95% of nominal value	<input type="checkbox"/>	
	- processing of alarm limits (color)	<input type="checkbox"/>	
	- hysteresis	<input type="checkbox"/>	

5.17. REDUNDANCY AND DIAGNOSTIC FUNCTION

The SAS system is designed for a hot/hot configuration. To fulfil this functionality following test will be performed:

5.17.1. SAS – SERVER REDUNDANCY

Purpose

In case of server failure the connected HMI operator workstations must switch to the healthy server.

Setup

Ensure setup as per approved SAS Architecture Drawing.

Procedure

1. With both Servers operational, verify that Clients are connected with their respective servers & can perform normal functions i.e. open different screens, alarm & trend screen.
2. On OWS-1 (Server1), Close the Server1 Application.
3. Check that the Alarm appears on the client.
4. Observe that Client1 is now connected with the Server2.
5. Start the Server1 application on OWS1, observe that Client1 is now connected with the OWS1 after some defined period of interval.
6. On OWS-2 (Server2), Close the Server2 Application.
7. Observe that Client2 are now connected with the Server1.
8. Check that Alarm appear on the client.
9. Start the Server2 application on OWS2, Observe that Client2 are now connected with the OWS2 after some defined period of interval.

Shutdown & Startup of Servers

Purpose

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

To verify that the HMI Redundancy is operational during the shutdown of the active server.

Setup

Ensure setup as per approved SAS Architecture Drawing.

Procedure

1. With both Servers operational, verify that OWS-1 relate to Server-1.
2. Shutdown Server-1. Observe that OWS-1 is now connected with the Server-2 and receives communications from the remote devices.
3. Startup Server-1 . Observe that there is no interruption to the Bay Level Devices. Restart the Client.
4. Observe that Client is now connected with the Server-1 (Primary Server) and receives communications from the remote devices.
5. Shutdown Server-2. Observe that OWS-2 is still connected with Server-1.
6. Startup Server-2. Observe that there is no interruption to the Bay Level Devices.

Voltage Level substation controller/Servers	Checked	Switch over time	Comments see log sheet no.
<p>Server1 faulty: Disconnect Server1 from LAN and generate new inputs (events and alarms) on BCU. Initiate control of any switching device.</p> <ul style="list-style-type: none"> • Check switchover of connected HMIs to Server 2 <input type="checkbox"/> • Check updating of information <input type="checkbox"/> • Check execution of command <input type="checkbox"/> • Check appearance of event/alarm <input type="checkbox"/> • Check fault indication of Server 1 <input type="checkbox"/> 			
<p>Server2 faulty: (Server1 healthy again) Disconnect Server2 from LAN and generate new inputs (events and alarms) on BCU. Initiate control of any switching device.</p> <ul style="list-style-type: none"> • Check switchover of connected HMIs to Server 1 <input type="checkbox"/> • Check updating of information <input type="checkbox"/> • Check execution of command <input type="checkbox"/> • Check appearance of event/alarm <input type="checkbox"/> • Check fault indication of Server 2 <input type="checkbox"/> 			

5.17.2. HMI OPERATOR WORKSTATION REDUNDANCY

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Each HMI operator workstation is independent of the other operator workstation and in case of failure the second workstation remains operational

	Checked	Comments see log sheet no.
HMI 1 faulty Disconnect HMI1 from LAN and generate newinputs (events and alarms) on BCU. Initiate control of any switching device. <ul style="list-style-type: none"> • <i>Check updating of information on HMI 2</i> • <i>Check execution of command</i> • <i>Check appearance on dot printer</i> • <i>Check fault indication of HMI 1</i> 	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	
HMI 2 faulty (HMI 1 healthy again) Disconnect HMI2 from LAN and generate newinputs (events and alarms) on BCU. Initiate control of any switching device. <ul style="list-style-type: none"> • <i>Check updating of information on HMI 1</i> • <i>Check execution of command</i> • <i>Check appearance on dot printer</i> • <i>Check fault indication of HMI 2</i> 	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	
HMI 1 and HMI 2 healthy again Check database synchronizing	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.17.3. ETHERNET SWITCH CONFIGURATION

Purpose

To verify that

- Proper configuration of Ethernet switches at the Station & Process level.
- To enable proper ring formation of the Ethernet switch in station & Process level
- To Document the Ethernet switch configuration considering the proper function of Ring network.

Typical Procedure:

- All IEDs & TCP/IP devices which are connected to non-RSTP ports, such ports should be configured as Edge port.
- Edge port should not be enabled with RSTP or Auto to reduce the ethernet switch processing.
- Only Point to Point port should be enabled with RSTP.
- Other than Edge port, all other unused ports should be disabled.
- Point to Point port & Discarding port need to be properly connected as per the System architecture.
- Ensure Bridging priority, Edge port, RSTP, VLAN configuration in Root & Non-Root Ethernet switches should be as per project requirement & Documented as below given example.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Sr. No	Panel Location	Switch Identification	Switch Port No	Bridge Priority	Edge Port	Switch to Switch Port	Un-used Port	RSTP	VLAN
1.	+R404A	K404	1	8192	No	Yes	No	Yes	As per Network requirement
2.	+R404A	K404	2	8192	No	Yes	No	Yes	As per Network requirement
3.	+R404A	K404	3	8192	No	Yes	No	Yes	As per Network requirement
4.	+R404A	K404	4	8192	No	Yes	No	Yes	As per Network requirement
5.	+R404A	K404	5	8192	Yes	No	No	No	As per GCB Table
6.	+R404A	K404	6	8192	Yes	No	No	No	As per GCB Table
7.	+R404A	K404	7	8192	Yes	No	No	No	As per GCB Table
8.	+R404A	K404	8	8192	Yes	No	No	No	As per GCB Table
9.	+R404A	K404	9	8192	Yes	No	No	No	As per GCB Table
10.	+R404A	K404	10	8192	Yes	No	No	No	As per GCB Table
11.	+R404A	K404	11	8192	Auto	Auto	Disabled	Yes	Default/Not applicable
12.	+R404A	K404	12	8192	Auto	Auto	Disabled	Yes	Default/Not applicable
13.	+R404A	K404	13	8192	Auto	Auto	Disabled	Yes	Default/Not applicable
14.	+R404A	K404	14	8192	Auto	Auto	Disabled	Yes	Default/Not applicable

Note: Control Room Switches has to be Kept as Root Bridge Switch and rest of the switch has to be followed the RSTP Philosophy. SAS Architecture has to be updated with these number if possible for better clarity.

	Checked	Comments see log sheet no.
Document Switch port configuration -IP address of the switch, Bridge numbering, VLAN, IP address, Edge port of as per project requirement considering GCB & considering Ring system	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.17.4. NETWORK REDUNDANCY

The reliability and security of the redundant LAN configuration will be checked.

Purpose

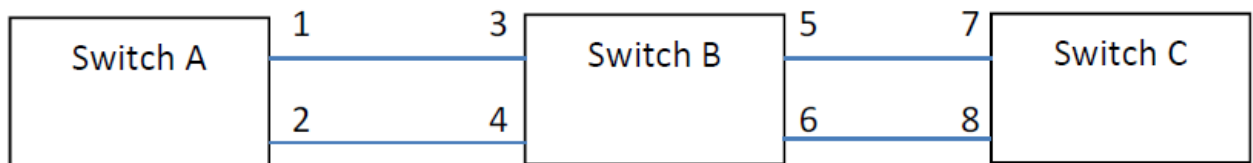
To verify that

- Ethernet connections in the Substation Automation System are functional and running.
- LAN Switch Redundancy is functional.

To establish that in the event of a loss in communications, the SAS device is OFFLINE. When the communications link is restored, the SAS device is automatically back to ON-LINE.

ETHERNET LAN REDUNDANCY CHECK

1. Choose a Switch in the LAN. Let it be Switch B in below fig having switches A & B adjacent to it. There are two ports, 3 & 4 of switch B connected to two ports, 1 & 2 of switch A. Similarly there are 2 other ports in switch B, 5 & 6 connected to ports 7 & 8 of switch C (as shown in figure).



2. On switch B Disconnect port 3 LAN cable. Verify that no device in the entire system fails to communicate.
3. On switch B Disconnect port 4 LAN cable. Verify that no device in the entire system fails to communicate.
4. On switch B Disconnect port 5 LAN cable. Verify that no device in the entire system fails to communicate.
5. On switch B Disconnect port 6 LAN cable. Verify that only those devices, which are connected to switch B, fail to communicate.
6. Restore the LAN cables in reverse order and check that communication of the devices above gets restored.
7. Repeat the above for all other switches in the Redundant RING LAN.

LAN Communication Functional Check test Results Log

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

S.NO.	Panel	Equipment	Communication check	Redundancy check
1	____KV BCU (Bay01/02/03---)			
2	____KV BCU (Bay01/02/03---)			
3	Networking Panel			

	Checked	Comments see log sheet no.
Checking Station Ethernet ring Checking functionality in case of disconnecting and connecting the ring at several points. Initiate control of any switching device. <ul style="list-style-type: none"> • Check redundancy. • Check fault indication from adjacent units. • Check appearance on HMI 1 & 2 • Check execution of command • Check dynamic animation of SCADA pictures (Communication ports status etc.) 	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	
Checking Bay Ethernet ring Checking functionality in case of disconnecting and connecting the ring at several points. Initiate control of any switching device. <ul style="list-style-type: none"> • Check redundancy. • Check fault indication from adjacent units • Check appearance on HMI 1 & 2 • Check execution of command • Check dynamic animation of SCADA pictures (communication ports status etc.) 	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	
Checking the communication of switches Checking functionality in case of disconnecting and connecting the Ethernet switches and router at several points. Initiate control of any switching device. (1x optical, 1x electrical, 1x 1GB port) <ul style="list-style-type: none"> • Check redundancy • Check fault indication from adjacent units • Check appearance on HMI 1 & 2 • Check execution of command • Check dynamic animation of SCADA pictures (communication ports status etc.) 	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

5.17.5. GATEWAY REDUNDANCY (IEC 101 & IEC104 PORTS)

The redundancy of the IEC 101/104 communication interface from the Gateways will be checked. As the real SCADA system is not available, two no of Laptops with the IEC TEST – Softwares are used to simulate the RCC& RSCC.

5.17.6. TIME SYNCHRONIZATION REDUNDANCY

Redundancy of GPS time synchronization is tested. One clock will be disconnected from the network. It is checked that the various devices are still time synchronized (i.e. by changing the time manually for a device and checking that it gets synchronized again).

Time synchronization redundancy	Checked	Comments see log sheet no.
Disconnect GPS time server 1 from the network Check availability of correct time synchronization Reconnect GPS time server 1 and disconnect time server 2 (any one of the IED/OWS internal clock) from the network Check availability of correct time synchronization	<input type="checkbox"/>	

5.17.7. SAFETY TAG FACILITY

It is checked that safety tag facility is realized in SCADA. A triangle with exclamation mark is set on the respective switching device.

	Checked	Comments see log sheet no.
Processing of safety tag facility	<input type="checkbox"/>	
Properties of safety tagging - 3 different types of safety tags - notebook facility (date, time, user, ...) - prevent of SCADA control	<input type="checkbox"/>	
Display on the - overview picture - individual bay display	<input type="checkbox"/>	
Check appearance on redundant server/operator	<input type="checkbox"/>	

5.17.8. MAINTENANCE MODE

It is checked that individual feeders can be set into maintenance mode. No control is possible, and no alarms/events can come up during the feeder is in maintenance mode, which is indicated by annunciation “MAINTENANCE MODE.”

	Checked	Comments see log sheet no.
Feeder is in “Maintenance Mode”	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

	Checked	Comments see log sheet no.
Check appearance on HMI Display	<input type="checkbox"/>	
Check control blocking	<input type="checkbox"/>	
Check suppression of data transmission	<input type="checkbox"/>	

5.17.9. IMPORT AND EXPORT OF ARCHIVED PROCESS DATA

The backup/ archiving function will be checked under this chapter. Data, which was outsourced as backup files will be imported into the runtime and displayed in the event list in conjunction with the filter function. During import mode no changes of any other archive type or date are possible. The “Archive” button starts blinking when an import succeeded. Afterwards the imported messages can be saved into a readable format (as *.csv or *.txt). The export button function will remove the backup database from the event list and the “Archive” button stops blinking.

	Checked	Comments see log sheet no.
Import from archive	<input type="checkbox"/>	
Export data to readable format to Excel (*.csv or *.txt)	<input type="checkbox"/>	
Export to archive	<input type="checkbox"/>	

5.18. ADDITIONAL TESTS

In this chapter the remote access to bay control unit and protection relays will be checked. In addition, some protection tests will be simulated for checking information recording in SAS-system.

	Checked	Comments see log sheet no.
Remote access to IED devices via DR PC:		
- Password security	<input type="checkbox"/>	
- Access/Load function with ability to change relay settings.	<input type="checkbox"/>	
- Download of fault records	<input type="checkbox"/>	
- Automatic download of DR (Built-in & Stand-alone) fault record with necessary S/w	<input type="checkbox"/>	
- Evaluation of Fault records with evaluation S/w	<input type="checkbox"/>	
- Connection to 3rd party relays	<input type="checkbox"/>	
Remote access to BCUs and via DR PC:		
- Password security	<input type="checkbox"/>	
- Access/Load function with ability to change relay settings	<input type="checkbox"/>	

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Information recording in SAS-system		
- Reset of trip lockout relay	<input type="checkbox"/>	
- Autoreclosing ON/OFF selection	<input type="checkbox"/>	
- Reporting of fault location		
- Hardcopy print (to paper and file)	<input type="checkbox"/>	

5.19. REMOTE DESKTOP

The remote desktop function is a feature of Windows. It is shown as an icon on the desktop of all PCs of this station. Pressing this button and a window will appear. Choose the desired PC by selecting its IP address; the remote desktop function opens the desktop of the desired PC. It is mainly used for configuring the station controllers and HMI servers from the Engineering PC.

Remote desktop	Checked	Comments see log sheet no.
Remote desktop functionality by using both IP & Their PC name	<input type="checkbox"/>	

5.20. TIME SYNCHRONIZATION

The time synchronization is checked under this chapter. The antenna of the GPS clock is disconnected. An alarm should be generated. Then the times of the devices is changed by hand for a few minutes only. Connect the antenna again. The devices have to synchronize again by themselves after some minutes and the alarm must disappear. The time synchronization test shall be performed by making GPS as the master clock for synchronizing all IED's present on ring network.

Procedure

1. Disconnect the GPS Receiver Antenna. Set the GPS Receiver to send Local Time.
2. Confirm that the External Time Display Unit displays this local time.
3. Confirm that IEDs Operator Workstations and Substation Gateway Times match this local time. This confirms that the SNTP packets are broadcast by the GPS receiver.
4. Confirm that GPS Receiver unsynchronized alarm is received in the workstations.
5. Power off the GPS receiver.
6. Verify that all IEDs are synchronized with any of the IED/OWS designated as redundant Timeserver.
7. Power on the GPS receiver.
8. Connect the GPS receiver Antenna. Verify that the GPS receiver is locked with satellite and GPS is updated to satellite time.

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Name:	Name:
Date:	Date:

9. Confirm that the External Time Display Unit, The IEDs, Operator workstations and the Substation Gateway are updated to the correct time of GPS.

Time synchronization	Checked	Comments see log sheet no.
OWS-1 & Server-1	<input type="checkbox"/>	
OWS-2 & Server-2	<input type="checkbox"/>	
DR PC	<input type="checkbox"/>	
Auxiliary System	<input type="checkbox"/>	
Reporting of Time synchronization alarm of connected all IEDs in the network	<input type="checkbox"/>	
Bay Control Unit	<input type="checkbox"/>	
Event list printer/ Hardcopy/ Logbook printer	<input type="checkbox"/>	

5.21. VALIDATION OF MEMORY AND DISK UTILIZATION

Purpose

To verify that the OWS/HMI have Memory and Disk Usage and allocation those are within the specification requirements. Processor and RAM shall be selected in such a manner that during normal operation not more than 30% capacity of processing and memory are used. Supplier shall demonstrate these features. The capacity of hard disk shall be selected such that the following requirement should occupy less than 50% of disk space:

1. Storage of all analogue data (at 15 Minutes interval) and digital data including alarm, event for two years and trend data for thirty(30) days,
2. Storage of all necessary software,
3. 500GB space for OWNER'S use.

Supplier shall demonstrate that the capacity of hard disk is sufficient to meet the above requirement.

Setup

Ensure that the Servers are running and functioning properly.

Validation of OWS Memory and Disk Utilization

Computer	Physical Memory	Hard Drive Free Space	PASS/FAIL
SERVER-1			PASS/FAIL
SERVER-2			PASS/FAIL
OWS-1			PASS/FAIL

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Computer	Physical Memory	Hard Drive Free Space	PASS/FAIL
OWS-2			PASS/FAIL
DR/EWS PC			PASS/FAIL
GATEWAY-1			PASS/FAIL
GATEWAY-2			PASS/FAIL

5.22. BCU INPUT/OUTPUT/ANALOG DATA RETRIEVAL

Configuration of data reporting at defined interval/cyclic and dead band shall be verified as per approved profile to evade hanging of both SCADA and IED.

The following are the procedures in the BCU I/O Data retrieval. The individual BCU Test result logs are to be filled up in the following sections.

Digital Input Retrieval

Purpose

To verify that the change of state of Digital Input points are updated in the BCU LHMI, the Operator Workstations and Master Station Simulator.

To verify that the Digital Inputs are mapped correctly as per the approved drawing.

Setup/Program

1. Connect the test jig to the BCU under test.
2. Go to the BCU LHMI Digital Inputs Display screen.
3. On the OWS-1 go to the relevant HMI screen.
4. On the OWS-2 go to Alarm/Event list.

Procedure

1. Select a Digital Input point on the BCU under test.
2. Change its state from 'OFF' to 'ON' (single points) or from 'OPEN' to 'CLOSED' (double points) by toggling the corresponding jig.
3. Verify that the state of this point in the BCU LHMI and HMI is changed correctly.
4. Verify that the state of this point in the OWS-2 event list screen is changed correctly.
5. For points configured with alarm, verify that alarms are displayed in the Alarm Screen of the OWS-2 with correct time stamp.
6. For points considered in the IEC 60870-101/104 List, verify that the state of this point in the Master Station Simulator is changed correctly with correct time stamp.
7. Change its state from 'ON' to 'OFF' (single points) or from 'CLOSED' to 'OPEN' (double points) by toggling the corresponding jig.
8. Repeats step 3 to 6

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Name:	Name:
Date:	Date:

9. Repeat 1 to 8 for all Digital Input points to be tested on this BCU.
10. Repeat steps 1 to 9 for all BCU's.
11. Data reporting shall be verified to evade hanging of both SCADA and IED.
Necessary simulation (including analog) shall be done by vendor.

Digital Output

Purpose

To verify that digital output operations are successfully executed.

To verify that the Digital Output points are mapped correctly according to the approved drawings & Data List.

Setup/Program

1. Connect the test jig to the BCU under test.
2. Go to the BCU MMI Digital Outputs Display screen.
3. On the OWS-1 go to the relevant HMI screen.
4. On the OWS-2 go to Alarm/Event list.

Procedure

1. Choose BCU to test. From the HMI workstation initiate digital output requests.
2. Verify that the corresponding output activated.

Software Interlock Logic

Purpose

To verify that software interlock logic for CBs and Isolators are operational based on simulated conditions.

Note: Since not all interlock conditions can be tested during FAT, other interlock inputs shall be simulated by shorting auxiliary contacts at the terminal blocks of the panels.

Setup

1. Set up the test jig to simulate software interlock positive and negative test conditions.
2. Set up shorting links to simulate other auxiliary contacts.
3. Refer approved drawings.

Procedure

1. Select a BCU to test.
2. Refer to the interlock conditions for testing. First set up a negative condition. Attempt to operate controls related to the interlock logic being tested. Verify that the interlock is successful.

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Date:	Date:

3. Set up for a positive test condition. Verify that interlock is successful when control operation is performed on related to the interlock logic being tested.

CB/ Isolators	CB/Isolators Interlock Negative Test Result	CB/Isolators Interlock Positive Test Result	CB/Isolator Condition	Checked

Note: Interlock involving GOOSE signal shall also be checked. It shall be ensured that absence of required GOOSE signal does not enable any interlocking condition. Interlock verification page for each control device as per TS based on the available input in the BCU to be prepared in HMI. Spare switching arrangement for Single phase reactor and transformer banks shall be verified by simulation and software interlocks to be verified.

5.23. SUBSTATION CONTROLLER DEVICE REPORTING

Purpose

To verify that the Substation Controller (Server/Client) is successfully communicating with the bay level devices using IEC 61850 protocol.

Setup

1. Ensure that the Server/Clients are running.
2. Go to the System Architecture Screen on Client.

Procedure

1. On the System Architecture screen, verify that the bay device status is Normal.
 2. Go to a remote device and disconnect the LAN cable, verify that the System Architecture screens shows the bay device is Failed.
 3. Connect the LAN cable. Monitor the communication between Server and remote device and verify that the IEC 61850 packets between the two TCP/IP addresses are passing through.
 4. Verify that the System Architecture Screen shows that the device is Normal.
- Repeat the above procedures for other devices.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

6. EWS/DR PC

6.1. SETTING AND CONFIGURING OF IEDS

Purpose

To verify that the IEDs configuration with proper tool for each type has been installed and all the IEDs (Protection, BCU, RTCC, CSD, FOTS & other TCP/IP devices) are accessible via the station ethernet ring. The DR PC should be able to change any configuration, settings, IP address & other parameters via TCP/IP should be possible.

Setup

1. Ensure that DR PC is running.

Procedure

(For example, for BCU)

1. Change some parameters in S/W for the BCU to test. Compile the Database for which parameters have been changed. (Wherever applicable)
2. Run S/W on the DR PC and select the compiled Database. Connect the BCU for which the parameters have been changed. (Wherever applicable)
3. Upload the database. (Wherever applicable)
4. Verify that the download is successful and check the DB version on the BCU. (Wherever applicable)

(For example, for Protection IED)

1. Change some parameters in S/W for the Protection IED to test. Compile configuration for which parameters have been changed. (Wherever applicable)
2. Connect the IED for which the parameters have been changed. (Wherever applicable)
3. Download the configuration or setting changed to the respective device. (Wherever applicable)
4. Verify that the download is successful and check the version on the IED. (Wherever applicable)

6.2. NETWORK MONITORING SYSTEM

Purpose

To verify that the Network Monitoring System (NMS) application software can perform the following functions on the LAN devices for both station bus & process bus:

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

- Configuration Management
- Fault Management
- Performance Monitoring
- Device Monitoring
- Log analysis
- Historical Data storage

Note:

1. **The Network Management System is based on Simple Network Monitoring Protocol (SNMP). Some background on this protocol is needed to understand how the application software works. If a separate network is available, then the each network has to have NMS separately example like Sample Values network in Process bus substation.**
2. **SNMP V3 may be implemented for the new projects. For extension projects, the existing SNMP version may be used.**

Procedure

1. Verify that NMS software monitors LAN devices statistics and present these using displays.
2. Verify that it maintains connectivity and device status, issues alarms on errors conditions. This can be verified in the Operator interface(OI) client screens.
3. Verify that it has tools for maintenance of addressed and links.

6.3. AUTO RECLOSE TEST
6.3.1. TEST FOR AUTO-RECLOSE SUCCESSFUL CASE

1. Select the Circuit Breakers of Main & Tie on which Auto reclose must be tested.
2. Ensure that the Circuit Breakers are in closed condition and Auto-recloser is in ON state and all interlock conditions for closing the breaker are satisfied.
3. Simulate 1-Phase trip, ensure that the corresponding phase of the Main & tie breakers open.
4. Ensure that the Main Circuit Breaker Auto recloses first with predefined dead time (1sec) and Tie-breaker auto recloses once the main breaker reclose cycle is completed as per the priority logic.
5. Ensure that once Auto-recloser is successful for main, the respective reclaim timer starts and Auto-reclose State goes back to Normal once the reclaim time is over and the same is applicable for TIE bay.
6. Put Auto-recloser of main CB in off position. Repeat steps 1 to 3. In this case ensure that Main CB does not go for Auto-reclose and tie CB Auto-reclosers without priority (1 sec)
7. Check that Auto-reclose does not take place for CB which are already in open condition. Check this for both main & tie CB.
8. Check that A/R does not take place for CB having A/R lockout condition (SF6 gas pressure/Oilpressure/spring discharge). The healthy CB associated with the feeder shall A/R successfully.
9. Repeat steps 4-6 for 3 phase auto reclose and single phase/3 ph. Auto reclose

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Date:	Date:

10. In case of single-phase fault for 3ph. Autoreclose selection, the single phase trip shall be connected to 3 ph. trip before autoreclose.

6.3.2.TEST FOR AUTO-RECLOSE FAILURE CASE

1. Repeat steps 1to 5 of successful case, Once the reclaim time starts, simulate another 1-Phase trip.
2. Ensure that the Auto-reclose enters Locking State and a 3-Ph tripping is issued to the both Main and Tie Breaker and all the 3-phases of the breaker open.
3. Repeat steps 1to 3 of successful case, Once the Auto-recloser cycle starts, before the dead time is over and close command is issued to the Main and Tie Breaker, Simulate another 1-ph trip. In this case also Auto-recloser enters Locking State and a 3-Ph tripping is issued to the both Main and Tie Breaker and all the 3-phases of the breaker open.
4. Repeat steps 1to 3 of successful case, Once the Auto-recloser cycle starts, before the dead time is over and close command is issued to the breaker, simulate the AR blocking signal, ensure that the Auto-reclose does not take place and Auto-recloser goes back to its Initial state.

7.DR CONFIGURATION

Check DR is configured as per TS & Latest standardized DR signal list configuration.

- i. Analog triggering level
- ii. Signal name and order
- iii. Pre-& Post fault time (Pre-fault time: min 500ms)
- iv. Triggering Channel
- v. Re-trigger option etc.

7.1. AUTO DR FUNCTIONALITY

Purpose

To verify that the automatic disturbance file is uploaded to DR PC when the disturbance is created.

Setup

1. Ensure that DR PC is running.
2. System Software should be running on the DR PC.

Procedure

1. Create the Disturbance on Main-1 &2, Verify that the disturbance has been created in the relay.
2. Ensure the Folders must be created for all Main-1&2, BCU folders based on the substation structure.
3. Observe that the Disturbance File (.cfg/.dat etc.) is automatically created in the DR PC.

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Signature:	Signature:
Name:	Name:
Date:	Date:

4. Open the Disturbance file with DR software.
5. As per the NTAMC AFAS requirement all the details of the IEDs has to be provided along with the location of the Folder created for each Protection IED
6. Verification of auto DR downloading functionality on triggering of waveform in each IED.
- 7.

8. IEC 60870-5-101/104 DATA RETRIEVAL

Purpose

To perform preliminary verification that the IEC 60870-5-101/104 Communication Ports are functional.

Setup/Program

- Ensure that the test equipment is in the FAT room.
- Use a Protocol Analyzer Test set to simulate an IEC 60870-5-101/104 Master Station polling with General Interrogation and data changes with 2 no of laptop. Use the Protocol Analyzer Test set to Monitor IEC 60870- 5-101/104 Telegram on the redundant serial communications links.

Procedure

1. Verify that communication is established with the simulator Protocol Analyzer Test set.
2. Verify that the simulator is sending requests on the primary channel and that the SAS Gateways is responding on both the primary (Main) and the secondary (Standby) channels.
3. Disconnect the simulator from the primary channel and connect it to the secondary channel; verify that the SAS Gateway will respond on both channels to requests received on the secondary channel.
4. Verify that data present at HMI should be same at Protocol Analyzer Test also.
5. Verify that all the configured required data points are sent by the gateway to the simulator.
6. Configuration of data reporting at defined interval/cyclic (generally analog without time tag), dead band shall be verified as per approved profile.

8.1. MASTER DIGITAL INPUTS RETRIEVAL

Purpose

To verify that the Substation Gateway is polled for Digital Input data correctly by the Master Simulator.

Procedure

1. Inject digital input changes to single point and double point inputs.
2. Verify change of the state in the Gateway Machine and Protocol Analyzer.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

8.2. MASTER ANALOG INPUTS RETRIEVAL

Purpose

To verify that substation gateway is polled for Analog Input data correctly by the Master Simulator.

Procedure

Inject Analog Inputs and verify that the Analog data are correctly received by the Master Simulator.

9. STATEMENT OF SYSTEM ACCEPTANCE

Upon satisfactory completion of all applicable tests specified in this document and the proper disposition of all properly documented and witnessed discrepancies resulting from tests specified in the procedure, the system, tested and witnessed by the POWERGRID is functionally accepted by POWERGRID.

The following documents has to be submitted for the clearance of the SAS wherever applicable.

Final FAT submission Verification log:

SI No.	Description	Drg No.	Checked
1	Standard Approved MQP		<input type="checkbox"/>
2	Approved FAT Procedure		<input type="checkbox"/>
3	GTP-General Technical Parameters		<input type="checkbox"/>
4	Complete SAS Architecture		<input type="checkbox"/>
5	Standard General Technical Particulars for SAS		<input type="checkbox"/>
6	Hardware specification		<input type="checkbox"/>
7	Functional Design Specification		<input type="checkbox"/>
8	VLAN Architecture drawing wherever applicable		<input type="checkbox"/>
9	Matrix for GOOSE messages for each feeder (with publisher& subscriber details, Mac id, APP Id, VLAN as required)		<input type="checkbox"/>
10	Matrix for SV (with publisher & subscriber details, SV ID, Destination mac and VLAN details) in case of Process Bus substation		<input type="checkbox"/>
11	Ethernet Network Configuration Document (RSTP details, VLAN details, Port details etc.)		<input type="checkbox"/>
12	IP Addressing Details		<input type="checkbox"/>
13	Single SCD File of the Entire substation		<input type="checkbox"/>

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

SI No.	Description	Drg No.	Checked
14	Exported HMI signal list file in spreadsheet/CSV format.		<input type="checkbox"/>
15	Exported NTAMC signal list file in spreadsheet/CSV format.		<input type="checkbox"/>
16	Common BCU/Alarm Panel-01		<input type="checkbox"/>
17	Common BCU/Alarm Panel-02		<input type="checkbox"/>
18	GA & Scheme of Networking Panel		<input type="checkbox"/>
19	CRP (Line/Trafo/BR/LR/Tie/BC/TBC/BS/Etc)		<input type="checkbox"/>
20	Product Manuals(Installation, Configuration, maintenance, Troubleshooting, detailed diagnostics etc.)		<input type="checkbox"/>
21	Control Room Lay-out		<input type="checkbox"/>
22	Switchyard Panel Room layout drawing		<input type="checkbox"/>
23	Bill of Quantity-Spares		<input type="checkbox"/>
24	Other applicable drgs (not listed above)	Attach the list as annexure	<input type="checkbox"/>

Note: A single SCD file shall be there for the entire substation. For extension projects too, the SCD file shall be a single file after integrating the newer IEDs.

Softcopy of Manuals Log:

Document Title	Doc. No.	Checked
Operation and Technical Guide for BCU, Gateway, Server, OWS Software		<input type="checkbox"/>
Operation and Technical Guide IED configuration softwares		<input type="checkbox"/>
Operation and Technical Guide NMS Software		<input type="checkbox"/>
Operation and Technical Guide Ethernet Switch		<input type="checkbox"/>
Operation and Technical Guide Time synchronizing Equipment		<input type="checkbox"/>
Operation and Technical Guide Router Cum Firewall		<input type="checkbox"/>
Operation and Technical Guide UPS/Inverter		<input type="checkbox"/>
Other applicable equipment Operational & Technical Guide		<input type="checkbox"/>

Softwares/Project Backups/License details Backup:

Software/License	Doc. No.	Checked
Protection Project Configuration- As Manufactured		<input type="checkbox"/>
HMI Project Database – As Manufactured		<input type="checkbox"/>

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

Software/License	Doc. No.	Checked
Gateway Project Database – As Manufactured		<input type="checkbox"/>
Ethernet Configuration – As Manufactured		<input type="checkbox"/>
Any other Configuration(NMS, Syslog, etc)- As Manufactured		<input type="checkbox"/>
HMI associated Software & their license		<input type="checkbox"/>
Gateway associated software & their License		<input type="checkbox"/>
MS office & license		<input type="checkbox"/>
NMS & their license		<input type="checkbox"/>
Protection & Control each type Software & license		<input type="checkbox"/>
CSD, FOTS, RTCC & Other Devices Software & license		<input type="checkbox"/>
Antivirus software & license		<input type="checkbox"/>
Printers software & license		<input type="checkbox"/>
GPS clock software & license		<input type="checkbox"/>
Other applicable equipment Operational & Technical Guide		<input type="checkbox"/>

10. DURATION OF FACTORY ACCEPTANCE TEST

The duration of the Factory Acceptance Testing will be mutually agreed depending upon the size of the substation.

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

11. INDICATION AND CORRECTION REPORT

Any comments should be added in “log sheets”; Along with the Clearance the Indication and Correction report with compliance has to be submitted to the respective Site/RHQ/CC AM.

INDICATION AND CORRECTION REPORT

LOG SHEET:

No.	Reference	Author	Date

Description

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date:

12. APPENDIX

GLOSSARY

BCU: Bay Control Unit
DR: Disturbance Recorder
EWS: Engineering Workstation
FAT: Factory Acceptance Test
FPT: Functional Performance Test
FST: Factory Simulation Test
GTW: Gateway
GPS: Global Positioning System
IED: Intelligent Electronic Device
NMS: Network Management (Monitoring) System
OWS: Operator Workstation
RCC: Remote Control Centre
RSCC: Regional System Co-ordination Centre
SAS: Sub-station Automation System
SAT: Site Acceptance Test
SCADA: Supervisory Control And Data Acquisition

POWERGRID Representative	Manufacturer Representative
Signature:	Signature:
Name:	Name:
Date:	Date: